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1	Injection molding of magneto-sensitive polymer composites
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11	
12	ABSTRACT
13	Magneto sensitive parts made of a thermoplastic elastomer reinforced with iron microparticles
14	were prepared by imposing a magnetic field during injection molding. In particular, an
15	aluminum mold was designed to host an electro-magnet able to apply a magnetic field during
16	the injection of the material into the mold and its subsequent solidification. Samples obtained in
17	the presence of magnetic field were characterized by a peculiar, aligned distribution of iron
18	particles along the magnetic field lines, and columnar structures of variable length were
19	obtained. The mechanical characterization showed that the samples in which the iron particles
20	were aligned had higher modulus compared to samples in which the particles were randomly
21	dispersed. The magnetic field induced an anisotropic structural reinforcement that imparted to
22	composite samples a magnetostrictive feature, namely the capability to sense the magnetic field
23	and to react with a shape change under the application of the magnetic field.
24	
25	Keywords
26	Injection molding, magnetic field, composites, mechanical characterization, magnetostriction

28 1. Introduction

Magneto-sensitive polymer composites are smart materials made by embedding magnetic particles, micrometric or nanometric in size, into a polymeric matrix. In presence of a suitable magnetic field, particles align themselves along magnetic field lines leading to an anisotropic structural reinforcement. This alignment confers to the material the characteristic of being "smart" in the sense it can react to an external stimulus by changing its properties in the desired way.

35 In the scientific literature, several magnetorheological (MR) composites based on polymers and 36 aligned magnetic particles (MP) have been proposed [1]. Magnetorheological composites are 37 smart materials able to quickly, continuously and reversibly respond to the application of a 38 magnetic field external stimulus with a change in their properties [2-7]. These smart materials 39 can be fluid or solid [8-10]. MR fluids exhibit a field-dependent yield stress and are 40 conventionally used for vibration control and suspensions in the automotive field. Bastola et al. 41 in 2017 [11] developed a new type of hybrid magnetorheological elastomers (H-MREs) as a combination of an MR fluid and an elastomer matrix by means of a 3D printing technology. 42 43 MR solids are usually prepared by mixing magnetic particles in viscous precursors of the solid 44 and, unlike the fluids, retain their shape after the molding process. They have field-dependent 45 stiffness and can be used in adaptive tuned variable-stiffness devices, soft actuators and artificial muscles [12, 13]. They include magnetorheological gels [14-16], foams [17-20] and elastomers. 46 47 In the last decades several authors focused their attention on magnetorheological elastomers 48 (MREs), materials obtained by embedding micro-sized magnetizable particles in an elastomeric matrix during the crosslinking process [21, 22]. The presence of a magnetic field during the 49 production of the elastomer object induces interactions between particles that promote an 50 anisotropic ordered configuration formed by particle chains aligned along the field direction. 51 52 Anisotropic MR elastomers with special chain structure of magnetic particles have attracted the 53 interest of the researchers and materials have been fabricated based on different matrices, i.e. silicone elastomers, hard natural or synthetic rubber and polyurethane [23-27]. 54

In 2003 Farade and Benine analyzed mechanical and magnetic properties of particle-filled silicon rubber produced by aligning the embedded particles in the elastomer by the application of a magnetic field when the cross-linking of the resin took place [22].

58 Guan et al. in 2008 [28] prepared and analyzed MRE consisting of carbonyl iron particles 59 displaced in a silicon rubber matrix. They proved that magnetostrictive effect (shape variation of 60 such materials during the application of a magnetic field) increases on increasing the volume 61 fraction of particles. Magnetostriction generally increases with increasing magnetic field and 62 orientation of particles influences the magnetostrictive performance significantly. In 2010 Wu et 63 al. [29] investigated the influences of carbonyl iron particle content on the microstructure, 64 thermal, mechanical and MR properties of PU MREs. They found that the chain-like structures, 65 obtained by alignment of the particles according to the magnetic field lines, becomes denser as 66 the iron content increases. Furthermore, they demonstrated that the orientation of carbonyl iron particles can greatly enhance the compressive strength of the composite, but the tensile 67 properties of PU MREs decrease. In 2017 Perales-Martínez et al. [30] studied the rheological 68 69 and mechanical properties of magnetorheological elastomer based on silicone rubber with 70 different contents of carbonyl iron micro-particles. They found that the enhancement of the 71 mechanical properties was achieved with the adding of 20% of carbonyl iron particles to the silicon rubber matrix, obtaining up to 111% of additional stretch and 95% of increment in 72 tensile strength compared to that of the bare material. 73

74 Until now, to these authors' knowledge, only magneto-sensitive elastomers produced by curing 75 the magnetizable particles/elastomeric matrix mixtures in presence of a magnetic field have been proposed [31]. In this work, the combination of magneto-sensitive elastomers concept to 76 the injection molding process is proposed. In fact, among polymer processing technologies, 77 injection molding allows large scale productions of 3D articles. The idea behind this work 78 79 involves the use of injection molding technology in order to make profit of its main advantage: 80 the ability to give arbitrary and complex shapes to the artifacts. In this way, if the polymer 81 viscosity is low enough, magnetic particles can be aligned by the application of an external

82	magnetic field. Gradients of mechanical properties inside the injection molded parts can be
83	obtained depending on the intensity and the magnetic field direction. To this aim, a special mold
84	has been designed and a preliminary rheological study has been made in order to choose the
85	elastomer suitable for the purpose.
86	
87	2. Materials and methods
88	A polyolefin elastomer, Engage 8402 supplied by DuPont Dow Elastomers (Midland, Michigan,
89	USA) was adopted in this work. Engage is an ethylene-octene copolymer that performs well in a
90	wide range of thermoplastic elastomer applications. The properties of the adopted polymer are
91	reported in Table 1.
92	
93	Table 1
94	Properties of Engage 8402 as provided by the supplier.

Property	Method	Unit	Typical value
Melt Flow Index (190°C/2.16 kg)	ASTM D-1236	dg/min	30
Total Crystallinity	-	%	34
Melt Temperature	DSC Melting Peak (Rate 10°C/min)	°C	96
Glass Transition Temperature	DSC Inflection Point	°C	-44
Flexural Modulus (2% Secant)	ASTM D-790	MPa	69.9
Density	ASTM D-792	g/cm ³	0.902

96 Carbonyl Iron Powder CIP SQ supplied by Basf (Ludwingshafen, Germany) was adopted as

- 97 filler in this work. These particles have performed well for magneto-sensitive polyurethane
- 98 foams [31]. The main properties of the adopted Carbonyl Iron Powder are: minimum Fe content

99 99.5 %, maximum C content 0.05 %, maximum C content 0.22 %, mean particle size lower than
10 microns.

101

102 2.1 Masterbatch preparation and Rheological measurements

103

104	A masterbatch with 50 % by weight of iron microparticles (particle size -325 meshes, assay
105	97%), supplied by Sigma Aldrich (Saint Louis, Missouri, USA) was produced with Engage
106	8402 by means of a twin screw extruder (type PTW100 from Haake Thermo GmbH, Germany).
107	Subsequently, in order to obtain a compound with 20 % by weight of iron particles, the
108	masterbatch was diluted with neat polymer directly in the injection molding machine. The
109	extrusions were conducted at 160°C, while the die temperature was set at 130°C.
110	Rheological properties were studied by means of a Haake Mars rotational rheometer (Thermo
111	Haake GmBH, Germany), rheological tests were performed on the neat Engage 8402 and
112	Engage 8402+50% Fe by weight (10% by volume) to select the best processing conditions.
113	These tests were carried out at different temperatures (160 °C, 180 °C and 200 °C) thus
114	obtaining the dependence of the complex viscosity, G' and G" on the oscillation frequency.
115	
116	2.2 Injection molding
117	A 70-ton Negri-Bossi injection molding machine (CANBIMAT 65/185, from Negri-Bossi SpA,
118	Italy) with a screw diameter of 25 mm and $L/D=22$ was used in this work. Clamping unit of the
119	injection molding machine consists of an aluminum mold expressly designed to host an

120 electromagnet which generates a magnetic field in the cavity (Figure 1).





122 Fig. 1. Sketch of the Aluminum mold with the custom electromagnet.

124 Aluminum is chosen because it does not interfere with the magnetic field and allows to preserve the spatial distribution of the magnetic field lines, in order to exploit them to properly align the 125 126 reinforcing particles. The magnetic field time profile was optimized to properly move the iron particles in linear aggregates just before the polymer consolidation during cooling in the mold. 127 The electromagnet (Figure 2), fixed to the stationary platen of the injection molding machine, 128 consists of two coils of copper wires windings (copper wire diameter 1.4 mm, tolerance 2 mm, 129 winding resistance is 6.7 Ohm) connected to a power supply (EA-PSI 8360-10 T) and a 130 laminated magnetic core to form an "iron circuit" for the magnetic field lines. The dimensions 131 of the electromagnet are a trade-off among magnetic performance, maneuverability and safe 132 operations of the injection molding machine, as shown in Fig. 2b. 133



- **Fig. 2.** a) Custom Electromagnet with a 140 mm airgap; b) aluminum mold hosting the
- 136 electromagnet
- 137

138 The magnetic core is laminated in order to avoid eddy currents effects. The iron sheets are

- 139 standard M300-35A ISO. Number of spires and geometry of the magnetic core allow to obtain a
- 140 magnetic flux of 1.3 mWb.
- 141 The cavity with dumbbell geometry is obtained on a circular insert mounted on the moving
- 142 mold. The dumbbell cavity, 3 mm thick, was dimensioned according to the Type V of ASTM D
- 143 638-03. The rotation of the circular insert allows to orient the dumbbell sample at different
- 144 angles with respect to the magnetic field lines (Figure 3).
- 145



147 Fig. 3. Moving mold with dumbbell geometry obtained on a circular insert. The blue arrows

148 refer to the direction of the MF given by the custom electromagnet.



160 **Table 2**

161 Processing condition for injection molding.

Temperature profile [°C]	
	200 - 210 - 220 - 220
(increasing distance from the hopper to the nozzle)	200 210 220 220
(consing answere i on the hopper to the house)	
Nozzle temperature [°C]	220
Mold temperature [°C]	45
Filling pressure (hydraulic system) [bar]	70
Screw rotation speed [rpm]	100
Back pressure (hydraulic system) [bar]	2
Injection speed [%]	30
Shot size [cm3]	2.3
Cooling time [s]	60
Iron content [% by weight]	20 - 50
Working current [A]	8 - 9
Working voltage [V]	115 - 120
Magnetic field "ON" time [s]	10

162

During the injection molding process, at the beginning of the injection phase, the power supply is switched on so that the desired magnetic field is generated. The magnetic field is kept active for 10 seconds, in order to allow the orientation of the iron particles within the molten polymer.

167 2.3 Scanning electron microscopy

168 After production, the samples were sectioned and analyzed by a LEO-EVO 50 Scanning

- 169 electron microscope (Zeiss, Germany) in order to observe the spatial distribution of iron
- 170 particles in the polymeric matrix. The section observed by scanning electron microscopy is the

171 central part of the narrow section.

173 *2.4 Mechanical properties*

174 Mechanical properties of the samples have been tested by a 5kN universal testing machine

- 175 (LRXplus, Lloyd, United Kingdom). Self-tightening grips (model TH243-20 from DGTS, Italy)
- 176 have been used for tensile tests with a column speed of 10mm/min. The internal load cells and
- 177 extensimeter have been used to measure forces and deformations.

178

179 **3. Results**

180 The rheological properties of neat Engage and Engage 8402+50% Fe by weight are shown in

181 Fig. 4, in which it is possible to note that 50% by weight of iron powder results in increased

182 viscosity of the material. The rheological results obtained at three temperatures (160°C, 180°C,

183 200°C) have been superposed, using an appropriate shift factor for each temperature, to obtain a

184 master curve. The shift factors (αT) used to make the master curves of pure Engage and

- 185 Engage+50% Fe are reported in Table 3.
- 186



187

Fig. 4. Rheological properties of neat Engage (thin lines) and Engage 8402+50% Fe by weight
(thick lines). Mastercurves at 180°C

191 **Table 3**

Temperature [°C]	Shift factor Pure Engage	Shift factor Engage+50% _w Fe
160	1.66	1.85
180	1	1
200	0.62	0.69

192 Shift factors of the mastercurves of pure Engage and Engage+50% Fe.

193

194 Samples obtained by injection molding with the application of a magnetic field were observed

195 by SEM in order to verify the degree of orientation of the particles. Figure 5 shows the

196 micrographs of the Engage 8402+Fe 50% by weight obtained by orienting the dumbbell at 0°,

 45° and 90° with respect to the direction of the magnetic field. The micrographs on the left

show the entire section of the sample, while those on the right side show a magnification of the

199 very central part of the corresponding image on the left.



201

Fig. 5. SEM micrographs of Engage 8402+Fe 50% by weight obtained by orienting the
dumbbell at 0°, 45° and 90° with respect to the direction of the magnetic field.

The images confirm that the iron particles are indeed oriented along the magnetic field direction, developing chain-like structures. The spatial arrangement of particles in the three different cases is also clearly visible: the chains are directed along a direction that exactly corresponds to the direction of the magnetic field during molding. Furthermore, the observation of the entire section of the sample allows the identification of distinct zones (Fig. 6): a central zone oriented in the direction of the magnetic field, an outer area that exhibits a random distribution of the particles, a partially oriented intermediate zone. This result may show that, in

- 212 perspective, it is possible to obtain different orientation of particles and morphology within the
- same molded part.



215

Fig. 6. Engage 8402+Fe 50% by weight, MF 90°: subdivision of the section into an oriented
central zone, an outer area with random distribution of the particles, a partially oriented
intermediate zone.

219

This spatial arrangement of particles is closely related to the temperature profile of the polymer melt inside the cavity. In particular, since the solidification proceeds from the sample surface toward the core, the internal layers remain at high temperatures for a longer time. The low temperature of the polymer melt in the outer area implies high viscosity, and thus the action of the magnetic field is not sufficient to allow an orientation and the particles are distributed without a particular order within the polymer. The presence of aligned particles in chain form can also be detected by placing the molded

- sample, free to move, under a magnetic field. In fact, when the magnetic field is activated, the
- sample instantly respond by moving and stopping in a position where the particle chains inside

are perfectly aligned with the applied magnetic field lines, similarly to a compass needle. The position that the samples take under a magnetic field indirectly confirms the effective alignment of the iron particles along the designed angle. Also NoMF samples instantly respond to the application of a magnetic field, but the direction is always that of the main flow during molding (namely MF 0°). This phenomenon is probably due to the fact that, even in absence of magnetic field during the foam injection, the iron particles can assume a certain anisotropic distribution, hence some degree of orientation, due to the flow.

236 The mechanical properties of samples were characterized in tension mode, in order to evaluate 237 the stiffness and the strength as function of the reinforcement spatial distribution. Figure 7 238 shows the stress-strain curves obtained by tensile test on pure Engage, Engage with 50% Fe by 239 weight without magnetic field (50% Fe, No MF) and Engage with 50% Fe oriented at 0°. Since the values of strain are considerable, the curves are expressed in terms of "true stress" and 240 "true strain". In particular, if L is the current length of the gage, L_0 is its initial value, P is the 241 load and A_0 is the initial cross-sectional area, the "true strain" was calculated as $\varepsilon = \ln(L/L_0)$ and 242 the "true stress" as $\sigma = P/A_0 L/L_0$. 243



244

245

Fig. 7. Stress-strain curves of pure Engage, Engage with 50% Fe by weight without magnetic
field (50% Fe, No MF) and Engage with 50% Fe oriented at 0° (50%Fe, MF 0°) (a); stressstrain curves of Engage with 50% Fe oriented at 0°, 45° and 90° (b).

The slope of the initial linear portion of the stress-strain curves represents the Young's modulus of the tested material. Figure 8 shows the Young's modulus of pure Engage, Engage with 20% and with 50% Fe by weight.



253

Fig. 8. Young's modulus of pure Engage and Engage with 20% and 50% by weight of iron
particles oriented at 0°. 45° and 90° with respect to the magnetic field direction.

256

Results without the application of any magnetic field and with magnetic field at 0° , 45° and 90° with respect to the flow direction are reported. It is possible to observe that the addition of iron particles increases the Young's modulus, and that it is higher in case of magnetic field at 0° with respect to the flow direction. In particular, the Young's modulus of Engage with 50 wt% and MF at 0° is 33% higher than that measured on NoMF sample with the same iron content.

262

263 Magnetostrictive behaviour

264 Samples injection molded at 45° with respect to the magnetic field direction were subjected to

further tests, in order to evaluate their smart "active" behavior. In particular, the custom

- 266 electromagnet was used and two MF 45° samples were positioned in the center of the magnetic
- 267 field and blocked on one side. When the magnetic field is activated, the two samples tend to

deform by aligning the chain-like structures along the direction of the magnetic field, thus 268 269 inducing a shape change. Samples are deformed upwards or downwards depending on the actual direction of the particles inside them (see the scheme reported in Fig. 9, which shows the 270 271 response of samples with 20 wt% and 50 wt% of Fe under a MF set at 45°). It is possible to observe that the samples with 20 wt % of Fe undergo an almost imperceptible deformation (Fig. 272 9, left), so the particle orientation is not enough to induce visible deformation. Vice versa, the 273 samples with 50 wt% of Fe (Fig. 9, right) undergo a visible deformation due to the tendency of 274 the chain-like structures to align with the magnetic field lines. In particular, they tend to bend to 275 move apart in one case (top pictures in Fig. 9) or to get closer in the other case (bottom pictures 276 in Fig. 9). This proved that the presence of chain-like structures induces a magnetostrictive-like 277 278 behavior in the injection molded samples, phenomenon applicable in valves or pumps design. 279



Fig. 9. Magneto-sensitivity tests on samples of Engage+20% Fe by weight (left) and

Engage+50% Fe by weight (right) with MF 45°. The schemes indicate the direction of the
particles inside the samples.

286 **5. Conclusions**

In this work, composite lightweight materials based on a polymeric matrix with embedded magnetic micro-particles have been developed by using a thermoplastic elastomer mixed with iron microparticles.

A new aluminum mold was designed and built in such a way to host an electromagnet, able to impose a magnetic field during the injection of the material into the cavity and its subsequent solidification.

293 The application of the magnetic field during the injection molding process allowed the

formation of columnar aggregates oriented along the magnetic field lines, which were clearly

visible by SEM.

296 These oriented structures make the samples able to orient, if placed in a magnetic field, in the

same direction of the magnetic field imposed during injection molding, like the needle of a

298 compass. It was also noticed that the system obtained without the application of a magnetic field

also responded to the application of a magnetic field due to some flow-induced orientation in

300 the direction of flow. This phenomenon was interpreted by considering that the iron particles

301 can assume a certain anisotropic distribution, hence some degree of orientation, due to the flow

302 of the polymer after entering the mold. It was observed that the addition of iron particles

increases the Young's modulus, which is even higher in case of magnetic field at 0° with respect

to the flow direction.

It was verified that the peculiar particle distribution imparted to the samples a magnetostrictive behavior, namely the ability to change shape in presence of an external magnetic field. This property may be exploited in several ways, such for instance in the production of valves or pumps activated in a contactless way by means of a magnetic fields.

309

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- 317
- 318 The raw/processed data required to reproduce these findings cannot be shared at this time as the data also
- 319 forms part of an ongoing study.
- 320
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